Prof. Dr. Alfred Toth

Elemente einer trajektischen Systemtheorie

1. In Toth (2025) hatten wir das vollständige System der $3^3 = 27$ ternären (triadisch-trichotomischen) semiotischen Relationen in Form von trajektischen Abbildungen der Form

$T = (1, 2, 3) \mid (1, 2, 3)$ mit $\mid = R((1, 2, 3), (1, 2, 3))$

dargestellt und und die semiotischen Relationen nach dem Vorschlag Walthers für Zeichenklassen (vgl. Walther 1979, S. 79) in Kompositionen dyadischer Teilrelationen zerlegt

$(3.x, 2.y, 1.z) = (3.x \rightarrow 2.y) \circ (2.y \rightarrow 1.z)$

$(z.1, y.2, x.3) = (z.1 \rightarrow y.2) \circ (y.2 \rightarrow x.3)$.

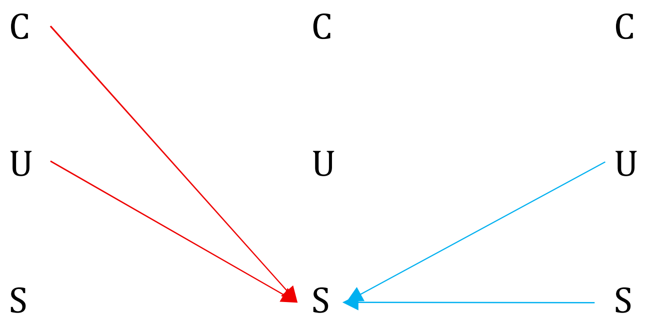
2. In der vorliegenden Arbeit benutzen wir die trajektische Abbildungstheorie als algebraische Grundlage einer ontischen Systemtheorie. Die Systemrelation ist definiert durch (vgl. Toth 2015)

$S^* = (S, U, C)$.

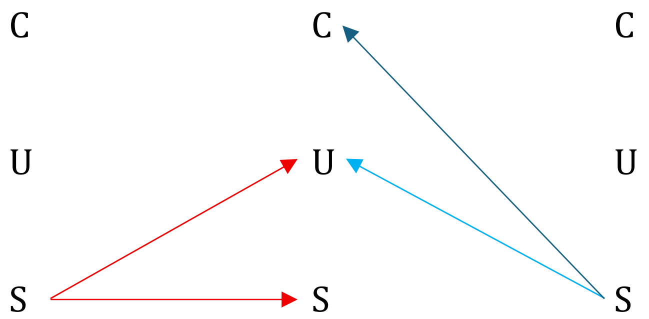
2. Systemrelationen

1. Systemrelation

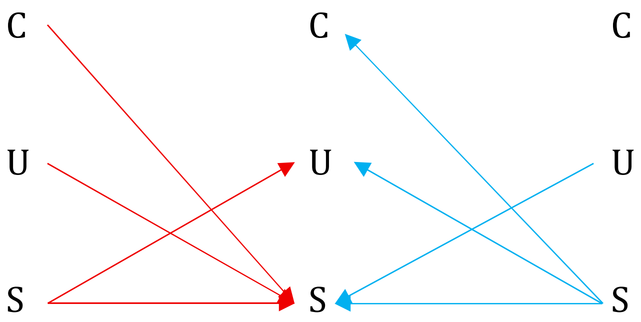
$S^* = (C.S, U.S, S.S)$



$DS^* = (S.S, S.U, S.C)$

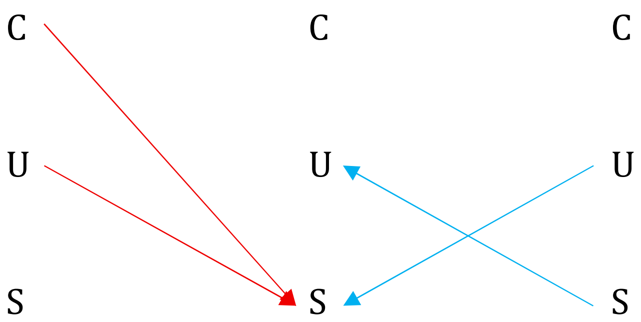


DS = [(C.S, U.S, S.S) × (S.S, S.U, S.C)]

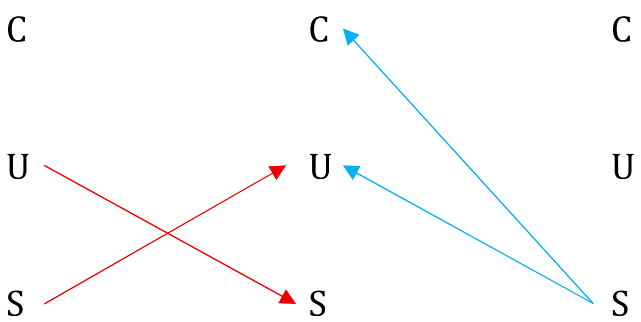


2. Systemrelation

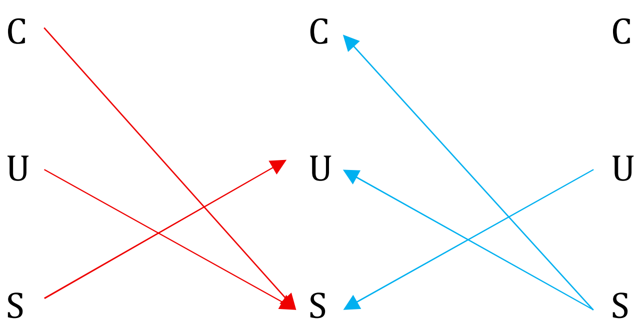
S* = (C.S, U.S, S.U)



DS* = (U.S, S.U, S.C)

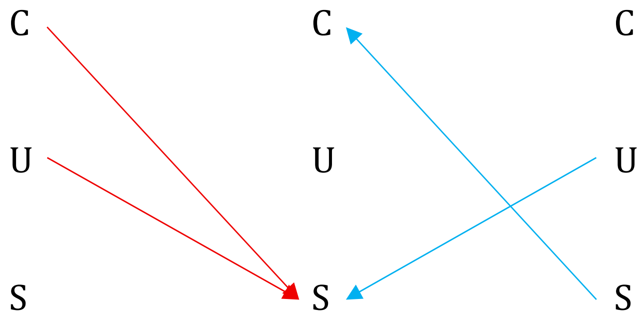


DS = [(C.S, U.S, S.U) × (U.S, S.U, S.C)]

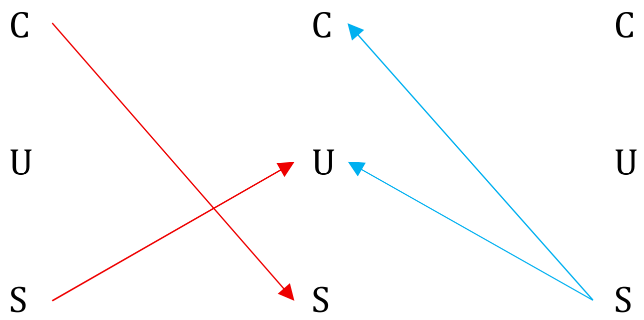


3. Systemrelation

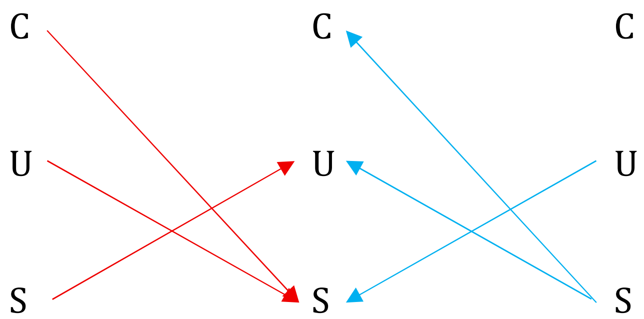
S* = (C.S, U.S, S.C)



DS* = (C.S, S.U, S.C)

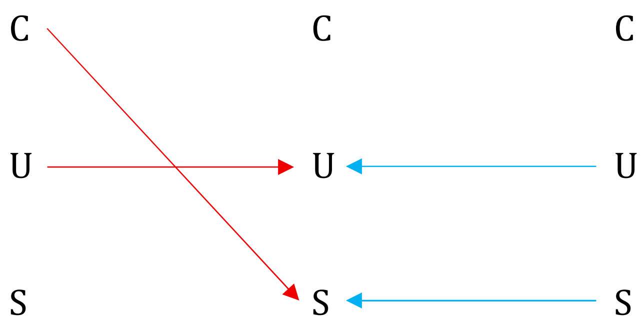


DS = [(C.S, U.S, S.C) × (C.S, S.U, S.C)]

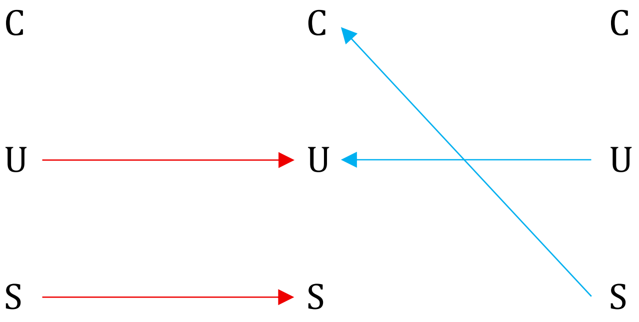


4. Systemrelation

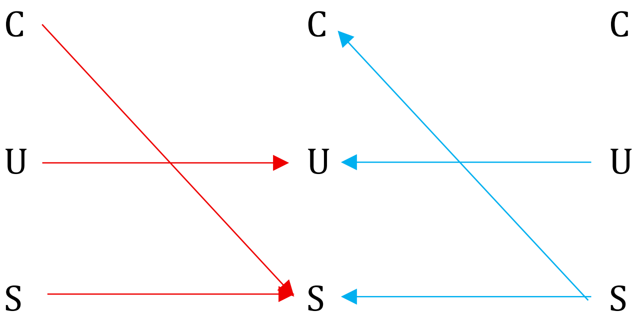
S* = (C.S, U.U, S.S)



DS* = (S.S, U.U, S.C)

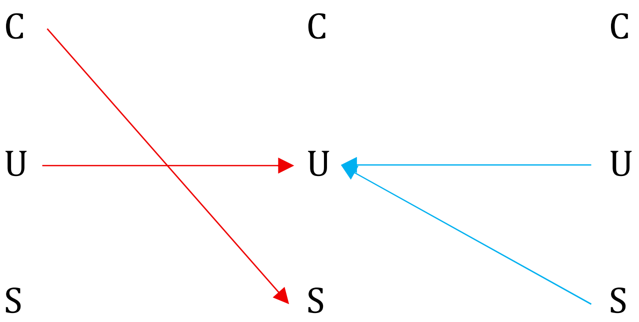


DS = [(C.S, U.U, S.S) × (S.S, U.U, S.C)]

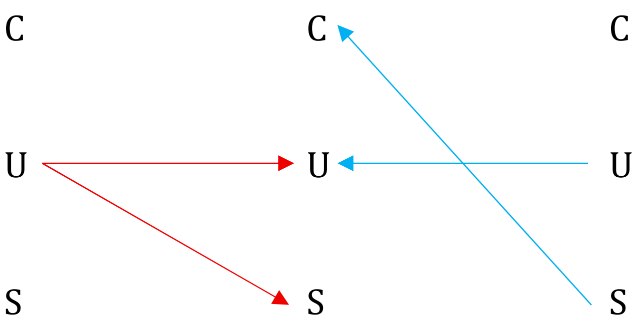


5. Systemrelation

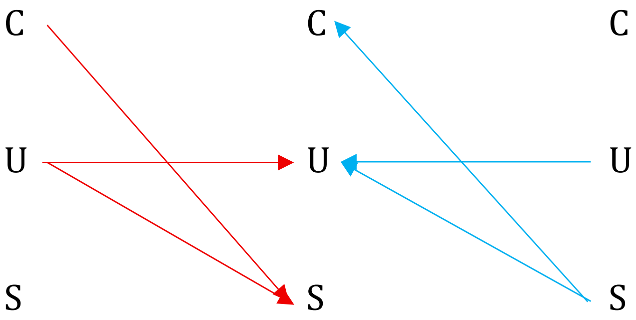
S* = (C.S, U.U, S.U)



DS* = (U.S, U.U, S.C)

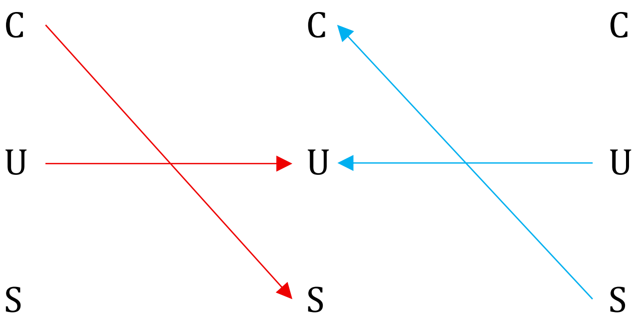


DS = [(C.S, U.U, S.U) × (U.S, U.U, S.C)]

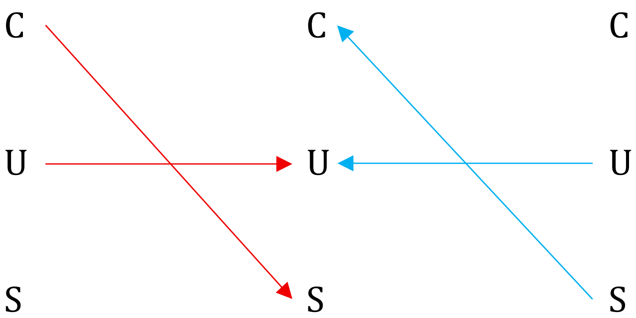


6. Systemrelation

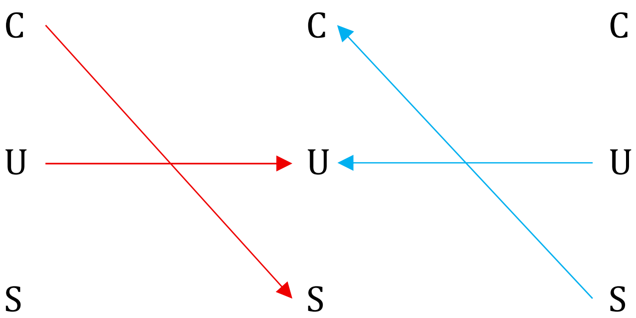
S* = (C.S, U.U, S.C)



DS* = (C.S, U.U, S.C)

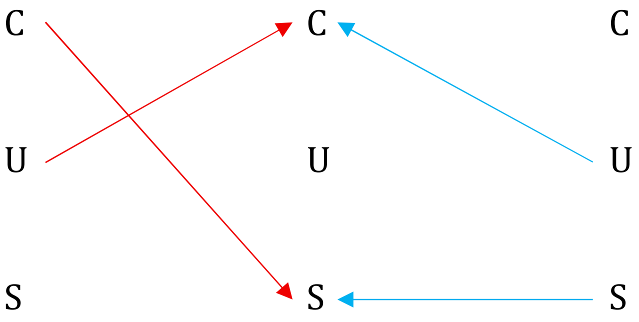


DS = [(C.S, U.U, S.C) × (C.S, U.U, S.C)]

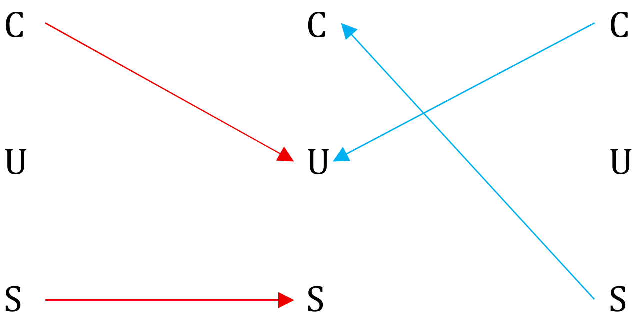


7. Systemrelation

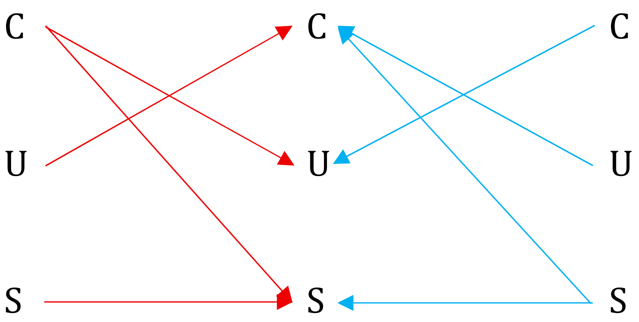
S* = (C.S, U.C, S.S)



DS* = (S.S, C.U, S.C)

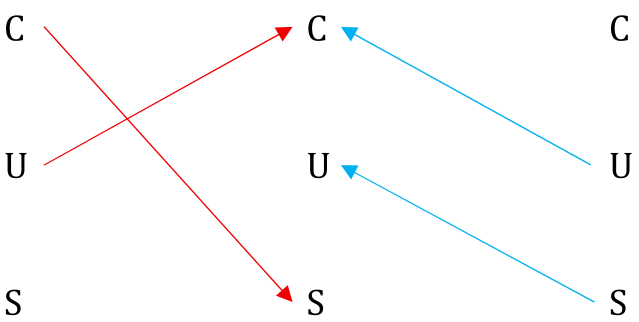


DS = [(C.S, U.C, S.S) × (S.S, C.U, S.C)]

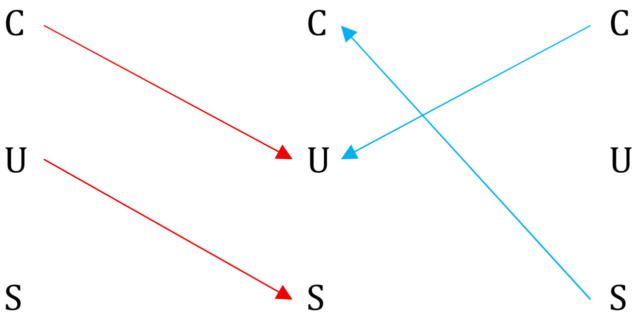


8. Systemrelation

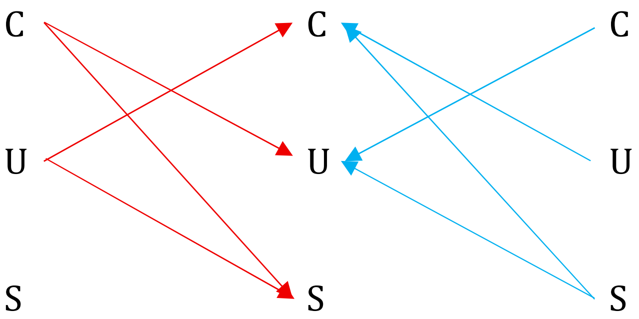
S* = (C.S, U.C, S.U)



DS* = (U.S, C.U, S.C)

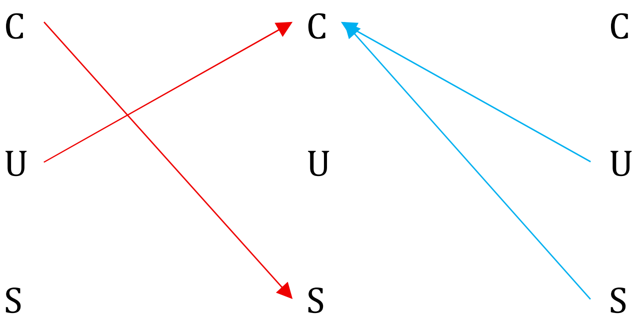


DS = [(C.S, U.C, S.U) × (U.S, C.U, S.C)]

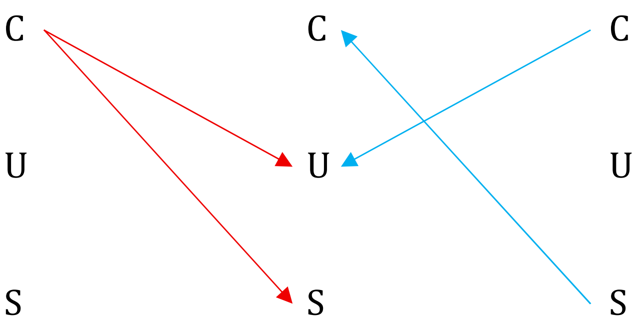


9. Systemrelation

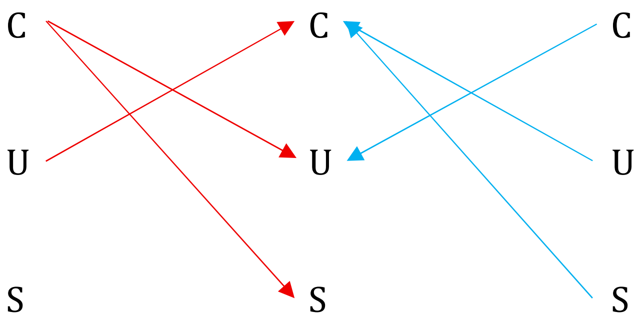
S* = (C.S, U.C, S.C)



DS* = (C.S, C.U, S.C)

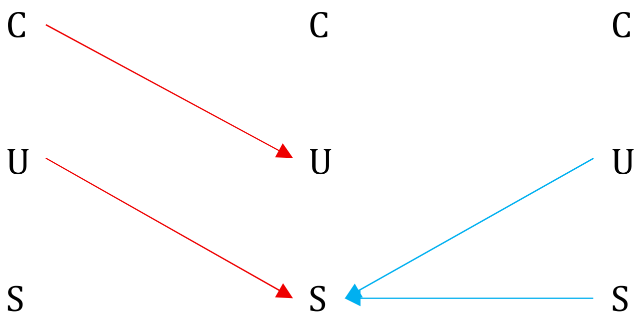


DS = [(C.S, U.C, S.C) × (C.S, C.U, S.C)]

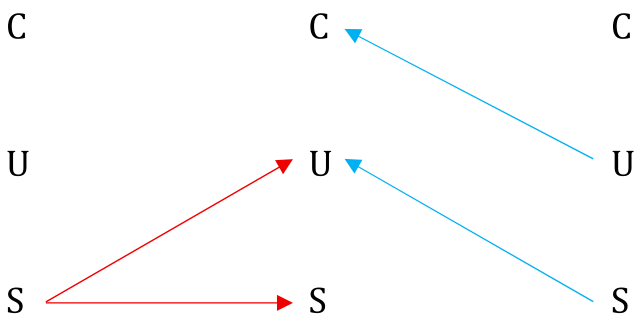


10. Systemrelation

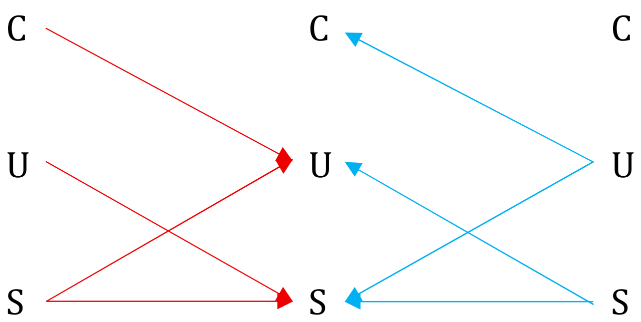
S* = (C.U, U.S, S.S)



DS* = (S.S, S.U, U.C)

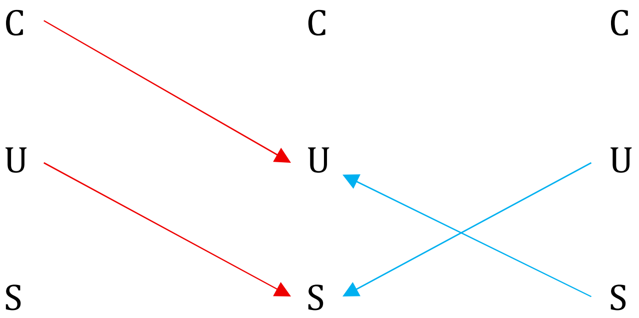


DS = [(C.U, U.S, S.S) × (S.S, S.U, U.C)]

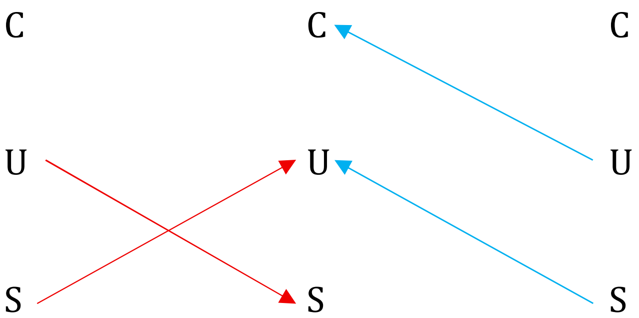


11. Systemrelation

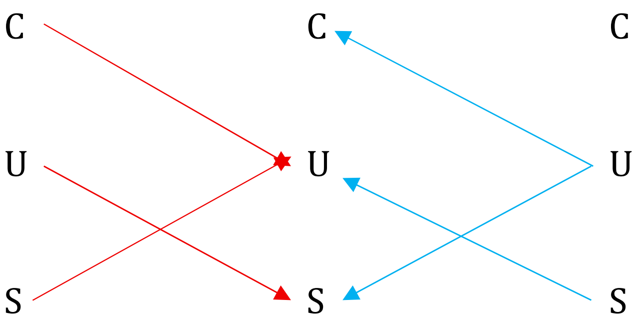
S* = (C.U, U.S, S.U)



DS* = (U.S, S.U, U.C)

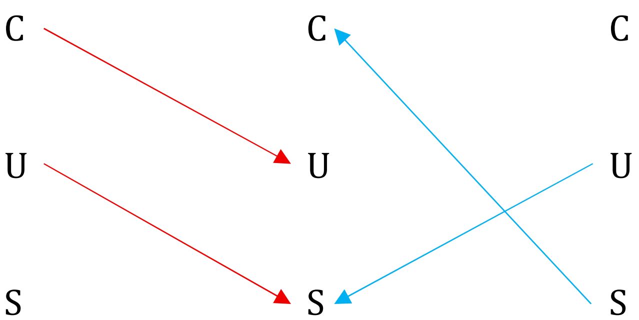


DS = [(C.U, U.S, S.U) × (U.S, S.U, U.C)]

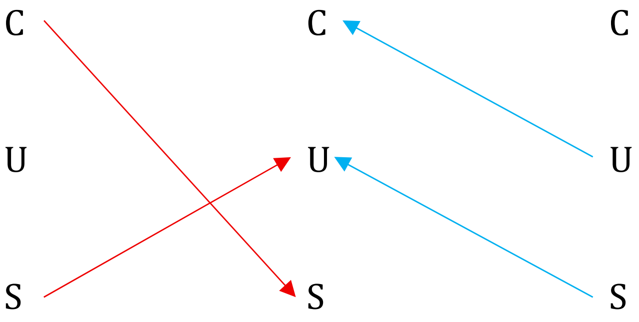


12. Systemrelation

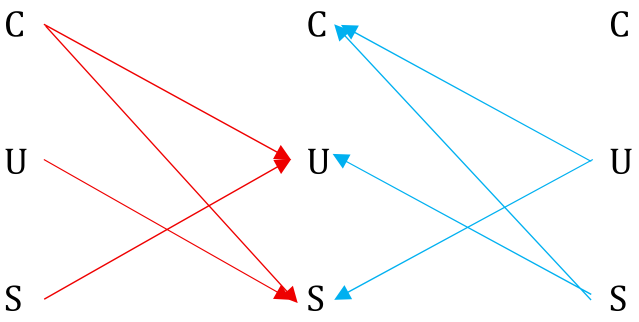
S* = (C.U, U.S, S.C)



DS* = (C.S, S.U, U.C)

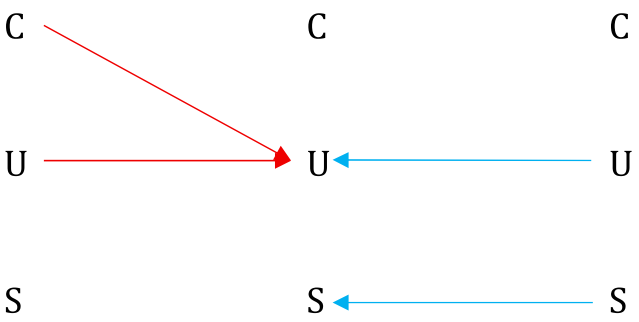


DS = [(C.U, U.S, S.C) × (C.S, S.U, U.C)]

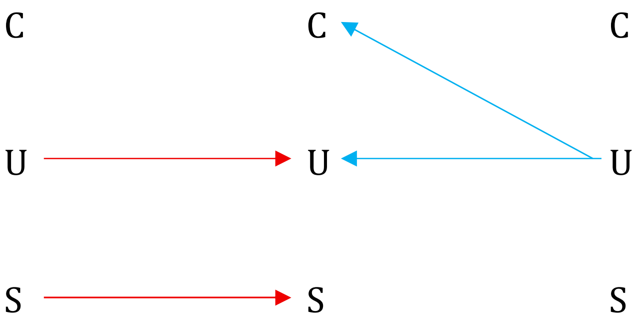


13. Systemrelation

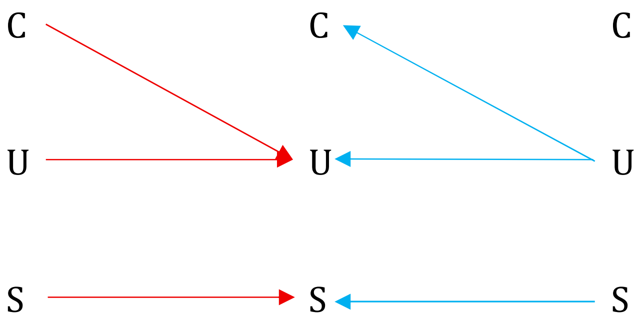
S* = (C.U, U.U, S.S)



DS* = (S.S, U.U, U.C)

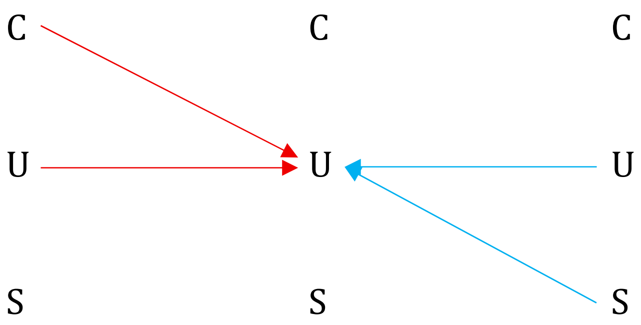


DS = [(C.U, U.U, S.S) × (S.S, U.U, U.C)]

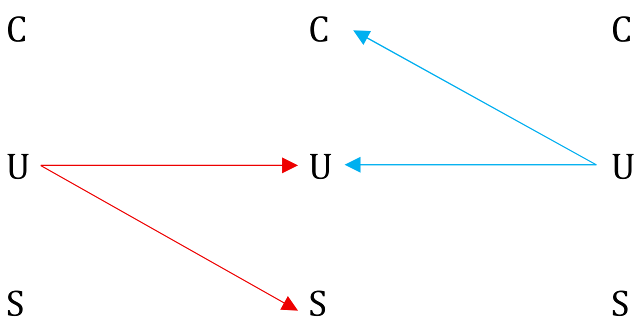


14. Systemrelation

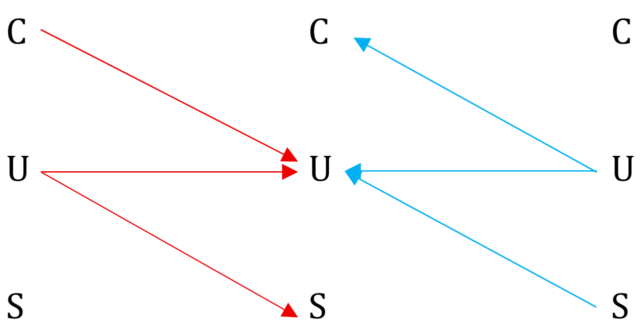
S* = (C.U, U.U, S.U)



DS* = (U.S, U.U, U.C)

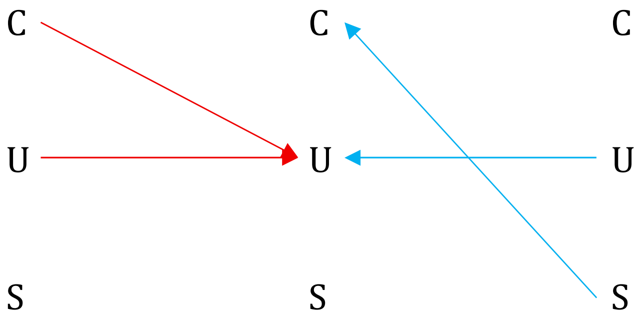


DS = [(C.U, U.U, S.U) × (U.S, U.U, U.C)]

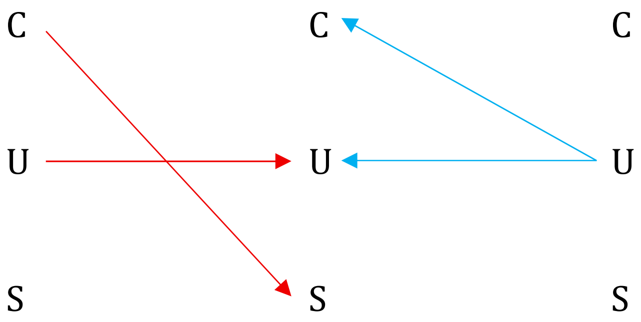


15. Systemrelation

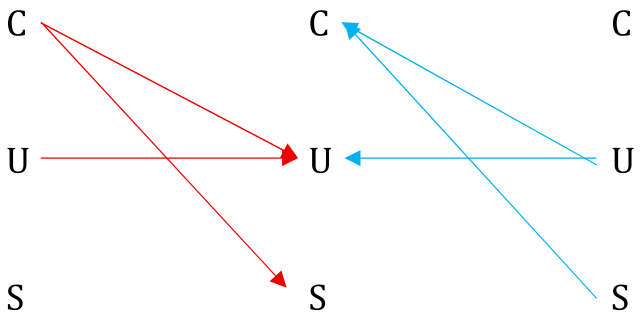
S* = (C.U, U.U, S.C)



DS* = (C.S, U.U, U.C)

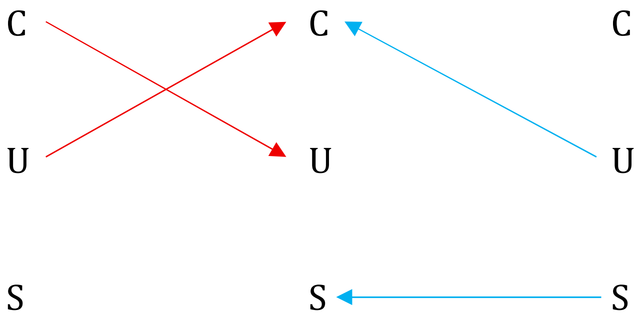


DS = [(C.U, U.U, S.C) × (C.S, U.U, U.C)]

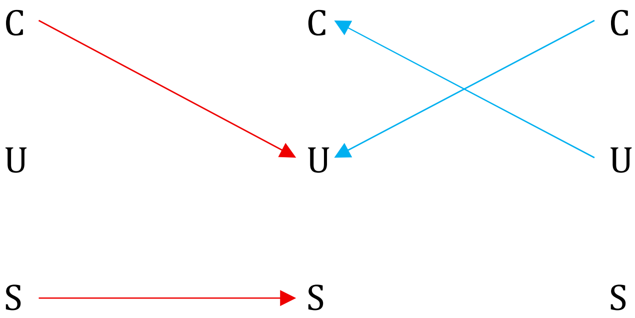


16. Systemrelation

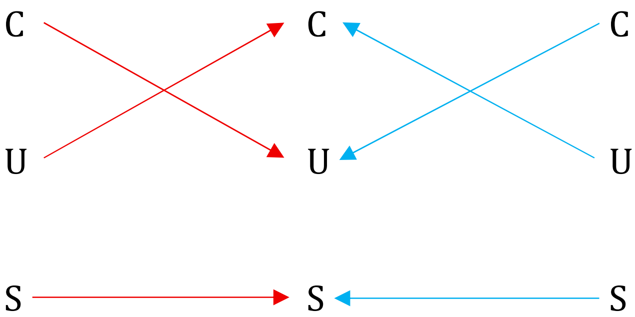
S* = (C.U, U.C, S.S)



DS* = (S.S, C.U, U.C)

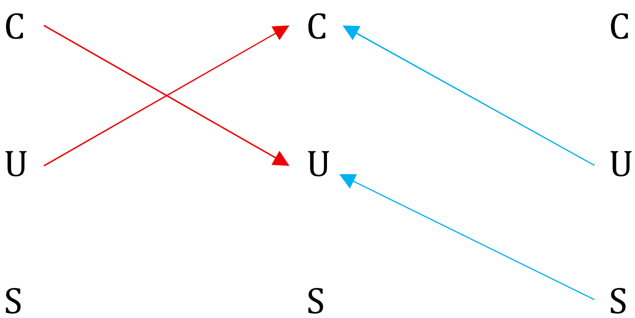


DS = [(C.U, U.C, S.S) × (S.S, C.U, U.C)]

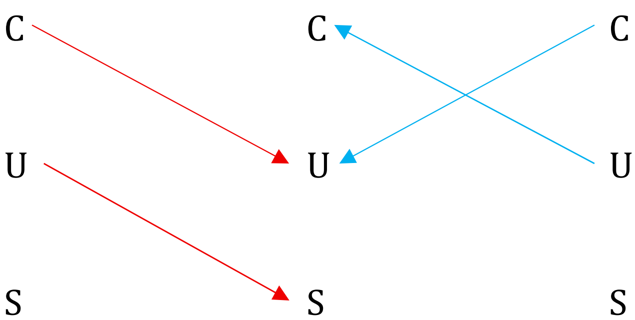


17. Systemrelation

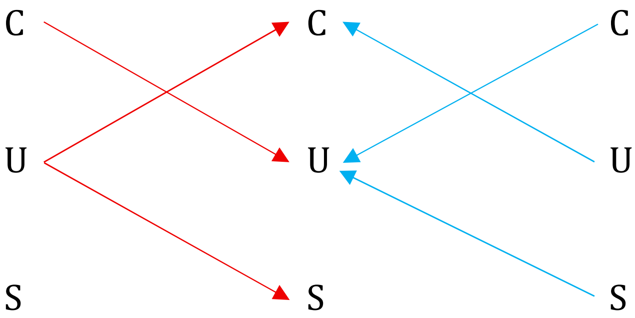
S* = (C.U, U.C, S.U)



DS* = (U.S, C.U, U.C)

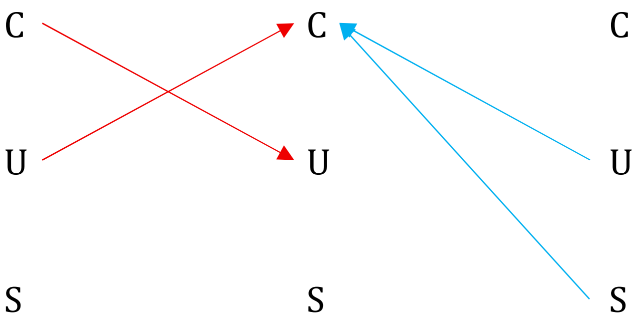


DS = [(C.U, U.C, S.U) × (U.S, C.U, U.C)]

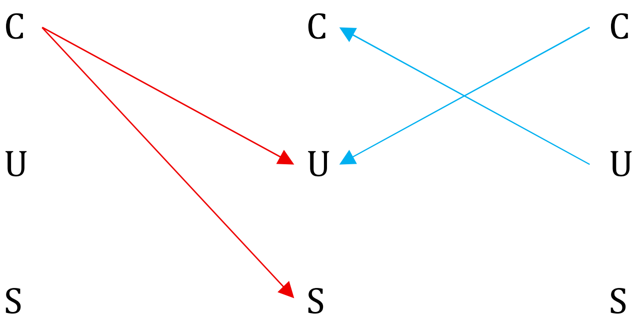


18. Systemrelation

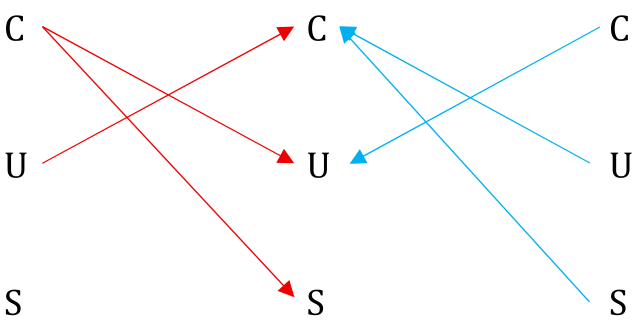
S* = (C.U, U.C, S.C)



DS* = (C.S, C.U, U.C)

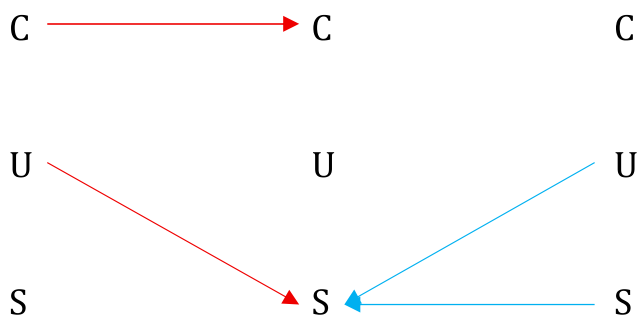


DS = [(C.U, U.C, S.C) × (C.S, C.U, U.C)]

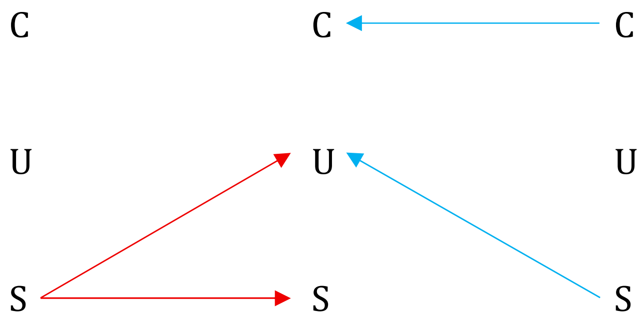


19. Systemrelation

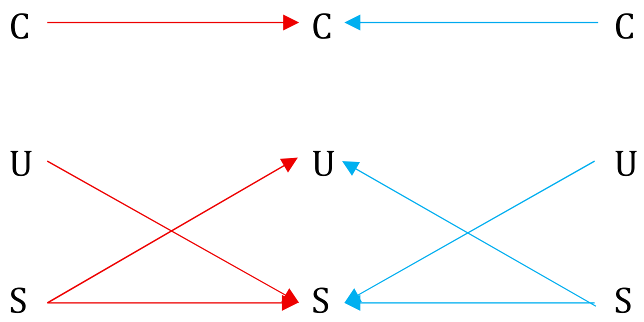
S* = (C.C, U.S, S.S)



DS* = (S.S, S.U, C.C)

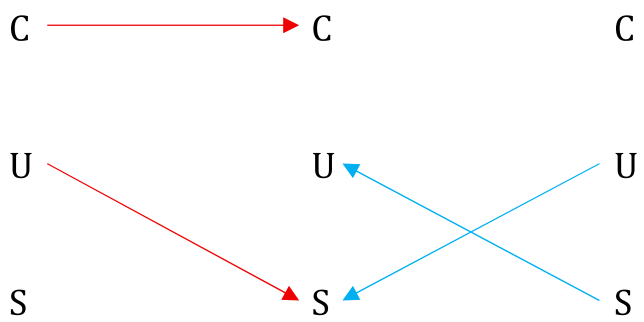


DS = [(C.C, U.S, S.S) × (S.S, S.U, C.C)]

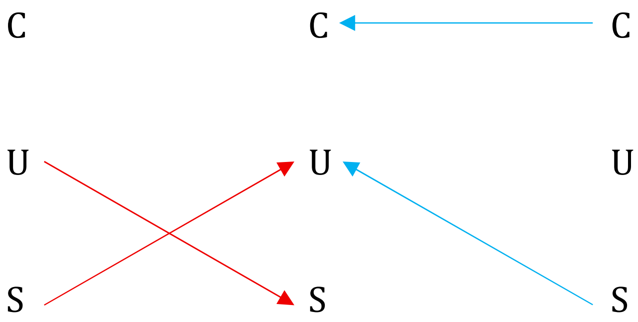


20. Systemrelation

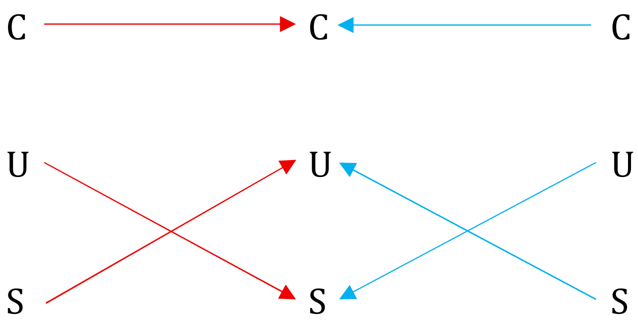
S* = (C.C, U.S, S.U)



DS* = (U.S, S.U, C.C)

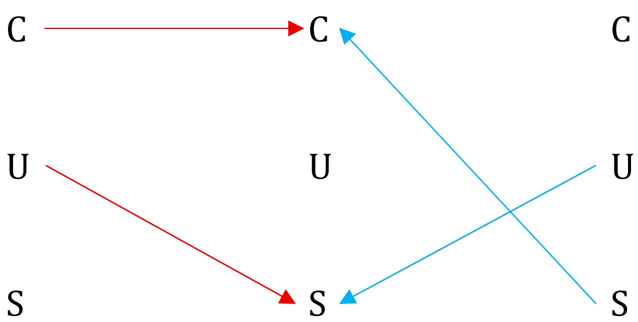


DS = [(C.C, U.S, S.U) × (U.S, S.U, C.C)]

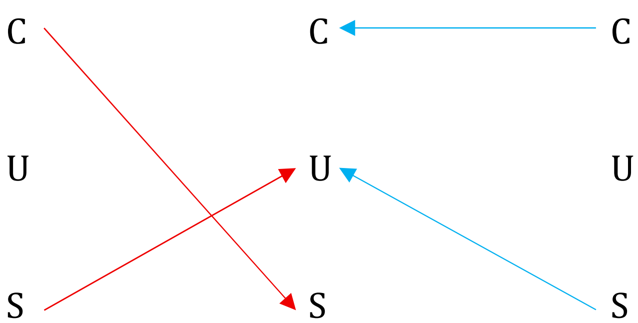


21. Systemrelation

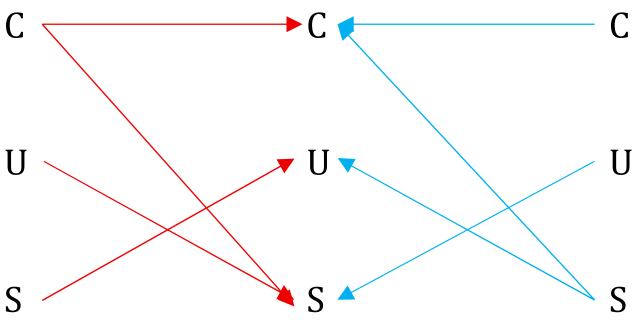
S* = (C.C, U.S, S.C)



DS* = (C.S, S.U, C.C)

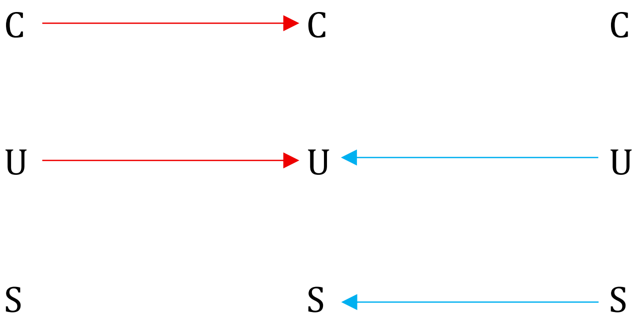


DS = [(C.C, U.S, S.C) × (C.S, S.U, C.C)]

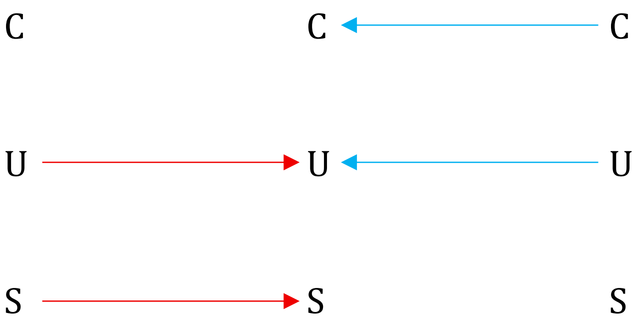


22. Systemrelation

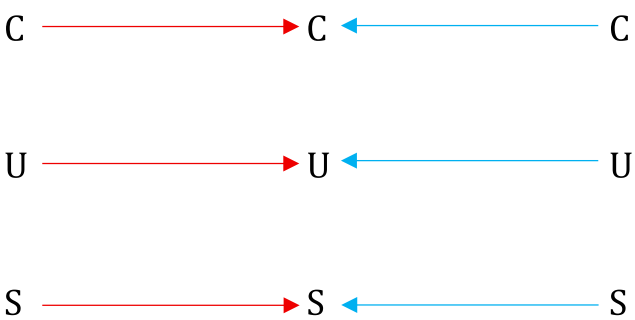
S* = (C.C, U.U, S.S)



DS* = (S.S, U.U, C.C)

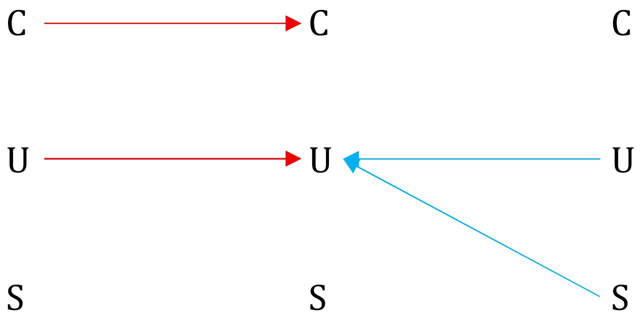


DS = [(C.C, U.U, S.S) × (S.S, U.U, C.C)]

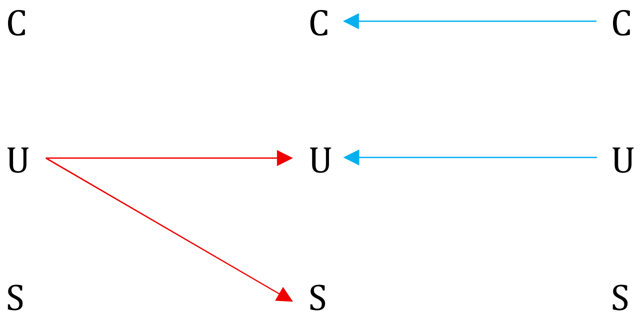


23. Systemrelation

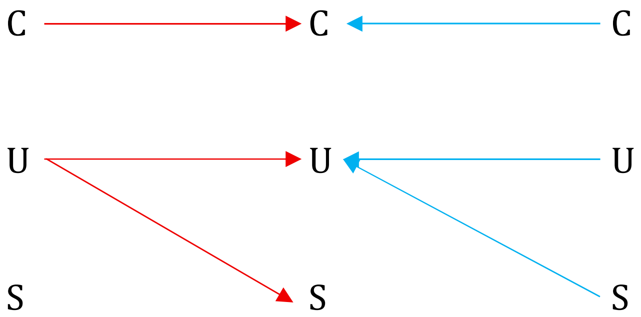
S* = (C.C, U.U, S.U)



DS* = (U.S, U.U, C.C)

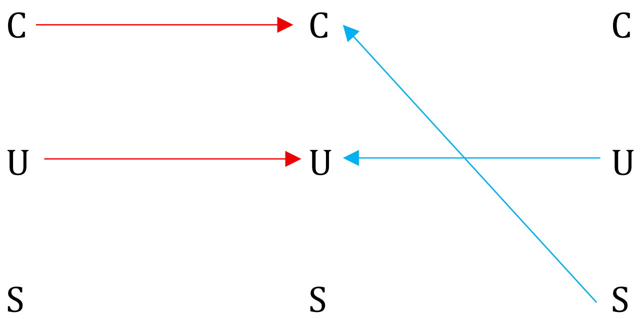


DS = [(C.C, U.U, S.U) × (U.S, U.U, C.C)]

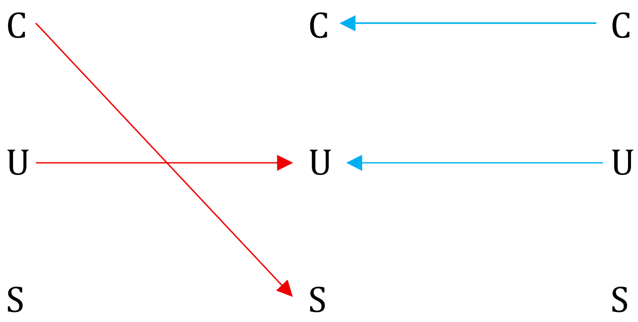


24. Systemrelation

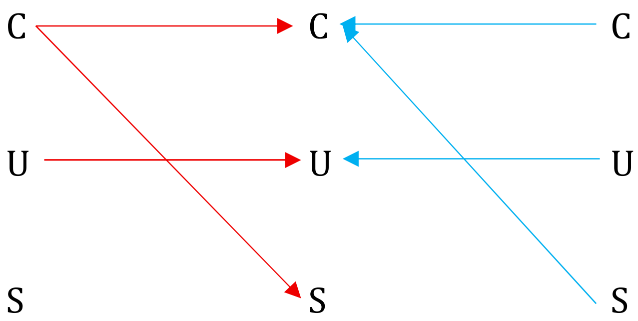
S* = (C.C, U.U, S.C)



DS* = (C.S, U.U, C.C)

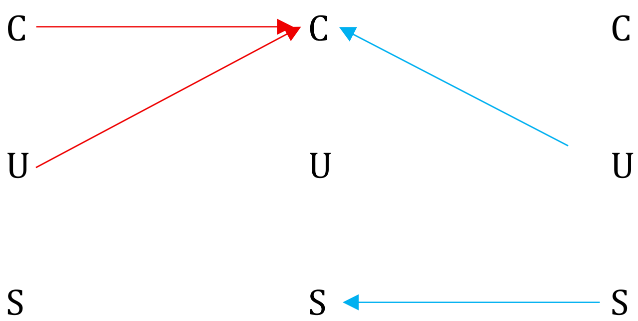


DS = [(C.C, U.U, S.C) × (C.S, U.U, C.C)]

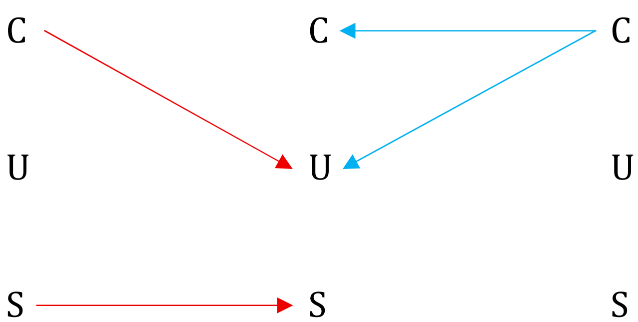


25. Systemrelation

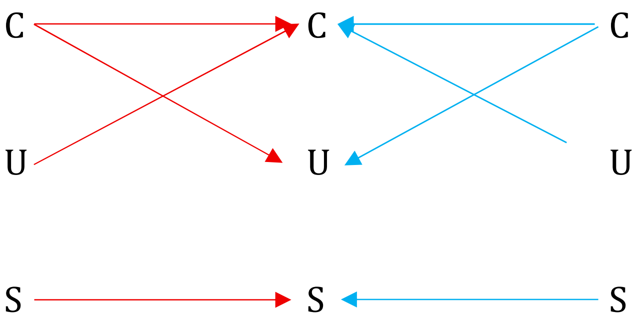
S* = (C.C, U.C, S.S)



DS* = (S.S, C.U, C.C)

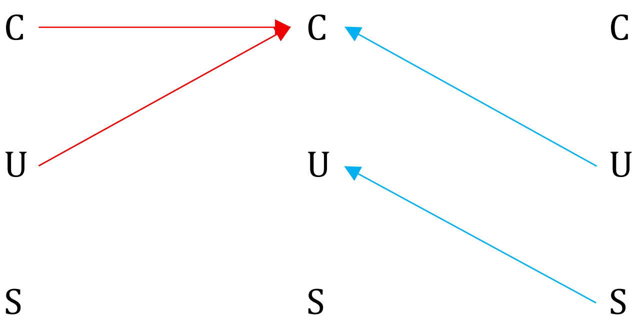


DS = [(C.C, U.C, S.S) × (S.S, C.U, C.C)]

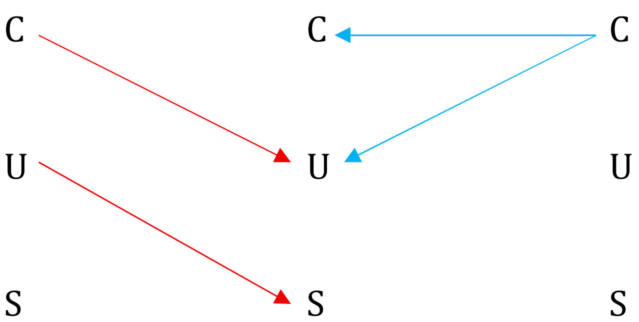


26. Systemrelation

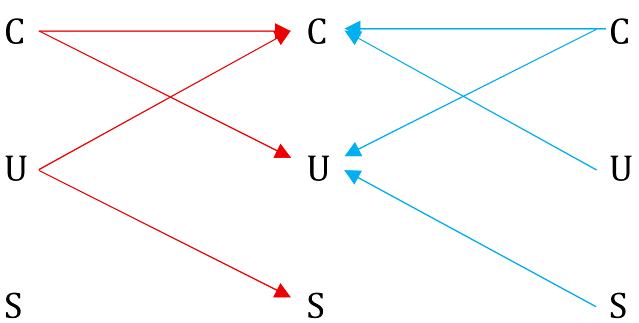
S* = (C.C, U.C, S.U)



DS* = (U.S, C.U, C.C)

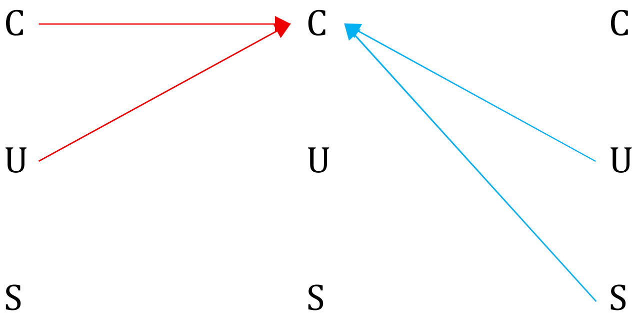


DS = [(C.C, U.C, S.U) × (U.S, C.U, C.C)]

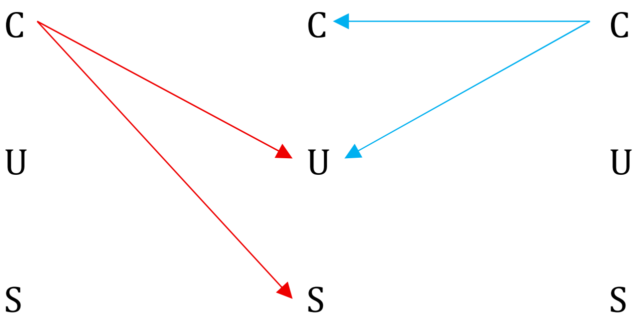


27. Systemrelation

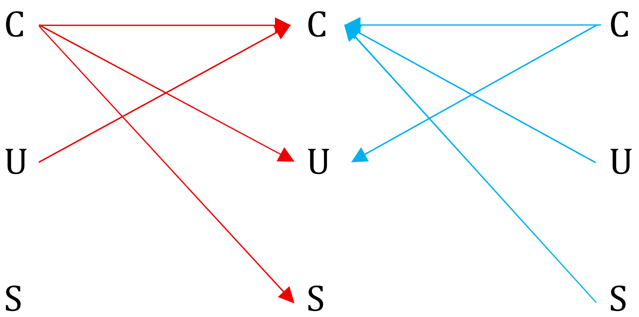
S* = (C.C, U.C, S.C)



DS* = (C.S, C.U, C.C)



DS = [(C.C, U.C, S.C) × (C.S, C.U, C.C)]



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